

Specifying Software Connectors

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Abstract. Orchestrating software components, often independently supplied, has assumed a central role in software construction. Actually, as relevant as components themselves, are the ways in which they can be put together to interact and cooperate in order to achieve some common goal. Such is the role of so-called software connectors: external coordination devices which ensure both the flow of data and synchronization restrictions within a component’s network. This paper introduces a new model for software connectors, based on relations extended in time, which aims to provide support for light inter-component dependency and effective external control.

1 Introduction

The expression *software connector* was coined by software architects to represent the interaction patterns among components, the latter regarded as primary computational elements or information repositories. The aim of connectors is to mediate the communication and coordination activities among components, acting as a sort of glueing code between them. Examples range from simple channels or pipes, to event broadcasters, synchronization barriers or even more complex structures encoding client-server protocols or hubs between databases and applications.

Although the area of component-based development [19, 25, 15] became accepted in industry as a new effective paradigm for Software Engineering and even considered its cornerstone in the years to come, there is still a need for precise ways to document and, even more, to reason about, the high-level structuring decisions which define a system’s software architecture.

Conceptually, there are essentially two ways of regarding *component-based* software development. The most wide-spreaded, which underlies popular technologies like, *e.g.*, CORBA [24], DCOM [14] or JAVABEANS [16], reflects what could be called the *object orientation* legacy. A component, in this sense, is essentially a collection of objects and, therefore, component interaction is achieved by mechanisms implementing the usual *method call* semantics. As F. Arbab stresses in [3] this

induces an asymmetric, unidirectional semantic dependency of users (of services) on providers (...) which subverts independence of components, contributes to the breaking of their encapsulation, and leads to a level of inter-dependence among components that is no looser than that among objects within a component.

An alternative point of view is inspired by research on coordination languages [13, 21] and favors strict component decoupling in order to support a looser inter-component dependency. In this view, computation and coordination are clearly separated, communication becomes *anonymous* and component interconnection is externally controlled. This model is (partially) implemented in JAVASPACEs on top of JINI [20] and fundamental to a number of approaches to componentware which identify communication by generic channels as the basic interaction mechanism — see, *e.g.*, REO [3] or PICCOLA [23, 18].

Adopting the latter point of view, this paper focuses on the specification of software connectors either as *relations* over a temporally labelled data domain (representing the flow of messages) or as *relations extended in time*, *i.e.*, defined with respect to a notion of internal state space intended to encode a memory of past computations. The second model can be regarded as an extension of the first one in the precise way that a labelled transition system extends a simple relation. Formally, we resort to coalgebraic structures [22] to model such *extended relations*, pursuing a previous line of research on applying coalgebra theory to the semantics of component-based software development (see, *eg.*, [5, 6, 17].).

The paper is organized as follows: section 2 introduces our semantic model for software connectors, illustrating it with the specification of one of the most basic connectors: the *asynchronous channel*. The model is further developed in section 3 which introduces a systematic way of building connectors by *aggregation* of *ports* as well as two combinators of connectors encoding, respectively, a form of *concurrent* composition and a generalization of *pipelining*. Section 4 illustrates the expressiveness of this model through the discussion of some typical examples from the literature. Finally, section 5 summarizes what has been achieved and enumerates a few research questions for the future.

Notation. The paper resorts to standard mathematical notation emphasizing a *pointfree* specification style (as in, *e.g.*, [9]) which leads to more concise descriptions and increased calculation power. The underlying mathematical universe is the category of sets and set-theoretic functions whose composition and identity are denoted by \cdot and id , respectively. Notation $(\phi \rightarrow f, g)$ stands for a conditional statement: if ϕ then apply function f else g . As usual, the basic set constructs are *product* ($A \times B$), *sum*, or disjoint union, $(A + B)$ and *function space* (B^A). We denote by $\pi_1 : A \times B \rightarrow A$ the first projection of a product and by $\iota_1 : A \rightarrow A + B$ the first embedding in a sum (similarly for the others). Both \times and $+$ extend to functions in the usual way and, being universal constructions, a canonical arrow is defined to $A \times B$ from any set C and, symmetrically, from $A + B$ to any set C , given functions $f : C \rightarrow A, g : C \rightarrow B$ and $l : A \rightarrow C, h : B \rightarrow C$, respectively. The former is called a *split* and

denoted by $\langle f, g \rangle$, the latter an *either* and denoted by $[l, h]$, satisfying

$$k = \langle f, g \rangle \Leftrightarrow \pi_1 \cdot k = f \wedge \pi_2 \cdot k = g \quad (1)$$

$$k = [l, h] \Leftrightarrow k \cdot \iota_1 = l \wedge k \cdot \iota_2 = h \quad (2)$$

Notation B^A is used to denote *function space*, *i.e.*, the set of (total) functions from A to B . It is also characterised by an universal property: for all function $f : A \times C \rightarrow B$, there exists a unique $\bar{f} : A \rightarrow B^C$, called the *curry* of f , such that $f = \text{ev} \cdot (\bar{f} \times C)$. Finally, we also assume the existence of a few basic sets, namely \emptyset , the empty set and $\mathbf{1}$, the singleton set. Note they are both ‘degenerate’ cases of, respectively, *sum* and *product* (obtained by applying the iterated version of those combinators to a nullary argument). Given a value v of type X , the corresponding constant function is denoted by $\underline{v} : \mathbf{1} \rightarrow X$. Of course all set constructions are made up to isomorphism. Therefore, set $\mathcal{B} = \mathbf{1} + \mathbf{1}$ is taken as the set of boolean values *true* and *false*. Finite sequences of X are denoted by X^* . Sequences are observed, as usual, by the head (*head*) and tail (*tail*) functions, and built by singleton sequence construction (*singl*) and concatenation (\frown).

2 Connectors as Coalgebras

2.1 Connectors

According to Allen and Garlan [1], an expressive notation for software connectors should have three properties. First, it should allow the specification of common patterns of architectural interaction, such as remote call, pipes, event broadcasters, and shared variables. Second, it should scale up to the description of complex, eventually dynamic, interactions among components. For example, in describing a client–server connection we might want to say that the server must be initialized by the client before a service request become enabled. Third, it should allow for fine-grained distinctions between small variations of typical interaction patterns.

In this paper a connector is regarded as *glueing device* between software components, ensuring the flow of data and synchronization constraints. Software components interact through anonymous messages flowing through a connector network. The basic intuition, borrowed from the coordination paradigm, is that connectors and components are independent devices, which make the latter amenable to external coordination control by the former.

Connectors have *interface points*, or *ports*, through which messages flow. Each port has an *interaction polarity* (either *input* or *output*), but, in general, connectors are blind with respect to the data values flowing through them. Consequently, let us assume \mathbb{D} as the generic type of such values. The simplest connector one can think of — the *synchronous channel* — can be modelled just as a *function* $[\bullet \dashv \longrightarrow \bullet] : \mathbb{D} \rightarrow \mathbb{D}$. The corresponding temporal constraint — that input and output occur simultaneously — is built-in in the very notion of a function. Such is not the case, however, of an *asynchronous channel* whose synchronization constraints entails the need for the introduction of some sort of temporal

information in the model. Therefore, we assume that, on crossing the borders of a connector, every data value becomes labelled by a *time stamp* which represents a (rather weak) notion of time intended to express *order of occurrence*. As in [3], temporal *simultaneity* is simply understood as *atomicity*, in the sense that two equally tagged input or output events are supposed to occur in an atomic way, that is, without being interleaved by other events.

In such a setting, the semantics of a connector C , with m input and n output ports, is given by a relation

$$\llbracket C \rrbracket : (\mathbb{D} \times \mathbb{T})^n \longrightarrow (\mathbb{D} \times \mathbb{T})^m \quad (3)$$

The *asynchronous channel*, in particular, becomes

$$\llbracket \bullet \dashrightarrow \bullet \rrbracket \subseteq (\mathbb{D} \times \mathbb{T}) \times (\mathbb{D} \times \mathbb{T}) = \{(d, t), (d', t') \mid d' = d \wedge t' > t\}$$

The explicit representation of a temporal dimension allows the modelling of non trivial synchronization restrictions. Relations, on the other hand, cater for non deterministic behaviour. For example, a *lossy* channel, *i.e.*, one that can loose information, modeling unreliable communications, is specified by a reflexive relation over $\mathbb{D} \times \mathbb{T}$, *i.e.*, a subset of the identity $\text{id}_{\mathbb{D} \times \mathbb{T}}$. This simple model was proposed by the authors in [7], where its expressive power and reasoning potential is discussed.

Note that \mathbb{D} has only the structure of a partial order. Prescribing more structure (for example requiring the order to be *dense*) will allow to tune the model towards more specific applications (for example in real-time programming). In any case, coming back to the asynchronous channel example, however, it seems difficult to express in this model the FIFO requirement usually associated to this sort of connectors. Such is the issue which motivated the model presented in the sequel.

The usual way to express such constraints, requiring a fine-grain control over the flow of data, resorts to *infinite* data structures, typically *streams*, *i.e.*, infinite sequences, of messages [4, 3] or [8]. An alternative, more operational, approach, to be followed here, is the introduction of some form of internal memory in the specification of connectors. Let U be the type of such memory, which, for this example is defined as a sequence of \mathbb{D} values, *i.e.*, $U = \mathbb{D}^*$, representing explicitly the buffering of received messages. The asynchronous channel is, then, given by the specification of two ports to which two operations over \mathbb{D}^* , corresponding to the reception and delivery of a \mathbb{D} value, are associated. The rationale is that the operations are activated by the arrival of a data element (often referred to as a message) to the port. Formally,

$$\begin{aligned} \text{receive} & : \mathbb{D}^* \times D \rightarrow \mathbb{D}^* \\ & = \frown \cdot (\text{id} \times \text{singl}) \\ \text{deliver} & : \mathbb{D}^* \rightarrow \mathbb{D}^* \times (\mathbb{D} + \mathbf{1}) \\ & = \langle \text{tl}, \text{hd} \rangle \end{aligned}$$

where Grouping together `receive` and `deliver`, leads to a specification of the channel as an elementary transition structure over \mathbb{D}^* , *i.e.*, a pointed *coalgebra* $\langle [] \in \mathbb{D}^*, c : \mathbb{D}^* \longrightarrow (\mathbb{D}^* \times (\mathbb{D} + \mathbf{1}))^{(\mathbb{D} + \mathbf{1})} \rangle$ where

$$\begin{aligned} \bar{c} = \mathbb{D}^* \times (\mathbb{D} + \mathbf{1}) &\xrightarrow{\text{dr}} \mathbb{D}^* \times \mathbb{D} + \mathbb{D}^* \xrightarrow{\overline{\text{receive} + \text{deliver}}} \mathbb{D}^* + \mathbb{D}^* \times (\mathbb{D} + \mathbf{1}) \\ &\xrightarrow{\simeq} \mathbb{D}^* \times \mathbf{1} + \mathbb{D}^* \times (\mathbb{D} + \mathbf{1}) \xrightarrow{[\text{id} \times \iota_2, \text{id}]} \mathbb{D}^* \times (\mathbb{D} + \mathbf{1}) \end{aligned}$$

Note how this specification meets all the exogenous synchronization constraints, including the enforcing of a strict FIFO discipline. The temporal dimension, however, is no more explicit, but *built-in* in the coalgebra dynamics. We shall come back to this in section 5. For the moment, however, let us elaborate on this example to introduce a general model of software connectors as coalgebras.

2.2 The General Model

A software connector is specified by an interface built from the aggregation of a number of *ports* represented by operations which regulate its behaviour. Each operation encodes the port reaction to a data item crossing the connector's boundary. Let U be data type standing for the connector's internal state space and \mathbb{D} a generic data domain for messages, as before. In such a setting we single out three kinds of ports with the following signatures:

$$\text{post} : U \longrightarrow U^{\mathbb{D}} \tag{4}$$

$$\text{read} : U \longrightarrow (\mathbb{D} + \mathbf{1}) \tag{5}$$

$$\text{get} : U \longrightarrow U \times (\mathbb{D} + \mathbf{1}) \tag{6}$$

where

- `post` is an input operation analogous to a write operation in conventional programming languages (see *e.g.*, [2, 21, 3]). Typically, a `post` port accepts data items and store them internally, in some form.
- `read` is a non-destructive output operation. This means that through a `read` port the environment might 'observe' a data item, but the connector's state space remains unchanged. Of course `read` is a partial operation, because there cannot be any guarantee that data is available for reading.
- `get` is a destructive variation of the `read` port. In this case the data item is not only made externally available, but also deleted from the connector's memory.

As mentioned above, connectors are formed by the aggregation of a number of `post`, `read` and `get` ports. According to their number and types one may obtain very specific connectors with well-defined behaviours. Let us see some possibilities.

Sources and Sinks. The most elementary connectors are those which have only one port. According to the orientation of the data they could be:

- Data *sources*, specified by a single **read** operation

$$\diamond_d = \langle d \in \mathbb{D}, \alpha_{\diamond_d} : \mathbb{D} \rightarrow \mathbb{D} + \mathbf{1} = \iota_1 \rangle \quad (7)$$

where α_{\diamond_d} is a read over state space $U = \mathbb{D}$, initialized with value d .

- Data *sinks*, ie, connectors which are always willing to accept any data item, discarding it immediately. The state space of this type of connectors is irrelevant and, therefore, modeled by the singleton set $\mathbf{1} = \{*\}$. Formally,

$$\blacklozenge = \langle * \in \mathbf{1}, \alpha_{\blacklozenge} : \mathbf{1} \rightarrow \mathbf{1}^{\mathbb{D}} = ! \rangle \quad (8)$$

where $!$ is the (universal) map from any object to the (final) set $\mathbf{1}$.

Binary Connectors. Consider, now, some experiments on aggregating pairs of ports of different types, assuming the corresponding operations conform the respective signatures and are defined over the same state space. This, in particular, enforces mutual execution of state updates.

- Consider, first, the aggregation of two **read** ports, denoted by read_1 and read_2 , with possibly different specifications. Both of them are (non destructive) observers and, therefore, can be simultaneously offered to the environment. The result is a coalgebra simply formed by their *split*:

$$c = \langle u \in U, \rho_c = \langle \text{read}_1, \text{read}_2 \rangle : U \rightarrow (\mathbb{D} + 1) \times (\mathbb{D} + 1) \rangle \quad (9)$$

- Let, now, $\gamma_c = \text{post}$ and $\rho_c = \text{read}$. Then

$$c = \langle u \in U, \langle \gamma_c, \rho_c \rangle : U \rightarrow U^{\mathbb{D}} \times (\mathbb{D} + 1) \rangle \quad (10)$$

- Replacing the **read** above by a **get** requires an additive aggregation to avoid the possibility of simultaneous updates leading to

$$c = \langle u \in U, \gamma_c : U \rightarrow (U \times (\mathbb{D} + 1))^{\mathbb{D}} \rangle \quad (11)$$

where

$$\begin{aligned} \overline{\gamma_c} &= U \times (\mathbb{D} + 1) \xrightarrow{\text{dr}} U \times \mathbb{D} + U \xrightarrow{\overline{\text{post} + \text{get}}} U + U \times (\mathbb{D} + 1) \\ &\xrightarrow{\simeq} U \times \mathbf{1} + U \times (\mathbb{D} + 1) \xrightarrow{[\text{id} \times \iota_2, \text{id}]} U \times (\mathbb{D} + 1) \end{aligned}$$

Channels of different kinds are connectors of this type. Recall the asynchronous channel example above, where ports identified by **receive** and **deliver** correspond to a **post** and a **get**, respectively. An useful variant is the *filter* connector which discards some messages according to a given predicate $\phi : \mathbf{2} \leftarrow \mathbb{D}$. The **get** port is given as before, i.e., $\langle \text{tl}, \text{hd} \rangle$, but **post** becomes a conditional over predicate ϕ , i.e.,

$$\text{post} = \phi \rightarrow \frown \cdot (\text{id} \times \text{singl}), \text{id}$$

– A similar care is required when aggregating two **post** ports:

$$c = \langle u \in U, \gamma_c : U \rightarrow U^{\mathbb{D}+\mathbb{D}} \rangle \quad (12)$$

where

$$\begin{aligned} \overline{\gamma_c} &= U \times (\mathbb{D} + \mathbb{D}) \xrightarrow{\text{dr}} U \times \mathbb{D} + U \times \mathbb{D} \\ &\xrightarrow{\overline{\text{post}_1 + \text{post}_2}} U + U \xrightarrow{\nabla} U \end{aligned}$$

In the examples above, dr is the right distributivity isomorphism and ∇ the codiagonal function defined as the *either* of two identities, *i.e.*, $\nabla = [\text{id}, \text{id}]$. A typical example of a connector with such a type is the *drain*, a symmetric connector with two inputs, but no output, points. Operationally, every message arriving to an end-point of a drain is simply lost. A drain is *synchronous* when both **post** operations are required to be active at the same time, and *asynchronous* otherwise. In both case, no information is saved and, therefore $U = \mathbf{1}$. Actually, drains are used enforce synchronizations in the flow of data. Formally, *asynchronous* drain is given by coalgebra

$$[[\bullet \xrightarrow{\nabla} \bullet]] = \mathbf{1} \xrightarrow{c} \mathbf{1}^{\mathbb{D}+\mathbb{D}}$$

where both **post** ports are modelled by the (universal) function to $\mathbf{1}$, *i.e.*, $\text{post}_1 = !_{U \times \mathbb{D}} = \text{post}_2$. The same operations can be composed in a product to model the *synchronous* variant:

$$[[\bullet \xrightarrow{\nabla} \bullet]] = U \xrightarrow{c} U^{\mathbb{D} \times \mathbb{D}}$$

where

$$\begin{aligned} \overline{c} &= \mathbf{1} \times (\mathbb{D} \times \mathbb{D}) \xrightarrow{\cong} \mathbf{1} \times \mathbb{D} \times \mathbf{1} \times \mathbb{D} \\ &\xrightarrow{\overline{\text{post}_1 \times \text{post}_2}} \mathbf{1} \times \mathbf{1} \xrightarrow{!} \mathbf{1} \end{aligned}$$

There is an important point to make here. In the last example two **post** ports were aggregated by a product, instead of the more common additive context. Such is required to enforce their simultaneous activation and, therefore, to meet the synchrony constraint in that connector. This type of port aggregation will also appear as a result of the concurrent composition of connectors through combinator \boxtimes to be introduced in section 3. In general, when presenting a connector's interface, we shall draw a distinction between *single* and *composite* ports, the latter corresponding to the simultaneous activation of two or more of the former.

The General Case. The examples above lead to the following shape for a connector built by aggregation of P **post**, G **get** and R **read** ports:

$$c = \langle u \in U, \langle \gamma_c, \rho_c \rangle : U \longrightarrow (U \times (\mathbb{D} + 1))^{P \times \mathbb{D} + G} \times (\mathbb{D} + 1)^R \rangle \quad (13)$$

where ρ_c is the split of the all the R **read** ports, *i.e.*,

$$\rho_c : U \longrightarrow (\mathbb{D} + 1) \times (\mathbb{D} + 1) \times \dots \times (\mathbb{D} + 1) \quad (14)$$

and, γ_c collects the two other type of ports characterized by the need to perform a state update, in the uniform scheme explained above for the binary case. Note that this expression can be rewritten as

$$U = \left(\sum_{i \in P} U^{\mathbb{D}} + \sum_{j \in G} U \times (\mathbb{D} + 1) \right) \times \prod_{k \in R} (\mathbb{D} + 1) \quad (15)$$

which is, however, less amenable to symbolic manipulation in proofs.

3 Combinators

In the previous section, a general model of software connectors as pointed coalgebras was introduced and their construction by port aggregation discussed. To obtain descriptions of more complex interaction patterns, however, some forms of connector composition are in need. Such is the topic of the present section in which two connector combinators are defined: one for *concurrent composition*, another which generalises *pipelining* capturing arbitrary composition of post with either read or get ports.

3.1 Concurrent Composition

Consider connectors c_1 and c_2 defined as

$$c_i = \langle u_i \in U_i, \langle \gamma_i, \rho_i \rangle : (U_i \times (\mathbb{D} + 1))^{P_i \times \mathbb{D} + G_i} \times (\mathbb{D} + 1)^{R_i} \rangle$$

with P_i ports of type *post*, R_i of type *read* and G_i of type *get*, for $i = 1, 2$. Their concurrent composition, denoted by $c_1 \boxtimes c_2$ makes externally available all c_1 and c_2 *single* primitive ports, plus *composite* ports corresponding to the simultaneous activation of *post* (respectively, *get*) ports in the two operands. Therefore, $P' = P_1 + P_2 + P_1 \times P_2$, $G' = G_1 + G_2 + G_1 \times G_2$ and $R' = R_1 + R_2$ become available in $c_1 \boxtimes c_2$ as its interface sets. Formally, define

$$c_1 \boxtimes c_2 : U' \longrightarrow (U' \times (\mathbb{D} + 1))^{P' \times \mathbb{D} + G'} \times (\mathbb{D} + 1)^{R'} \quad (16)$$

where

$$\begin{aligned} \overline{\gamma}_{c_1 \boxtimes c_2} &= U_1 \times U_2 \times (P_1 + P_2 + P_1 \times P_2) \times D + (G_1 + G_2 + G_1 \times G_2) \xrightarrow{\simeq} \\ & (U_1 \times (P_1 \times D + G_1) \times U_2 + U_1 \times U_2 \times (P_2 \times D + G_2) + U_1 \times (P_1 \times D + G_1) \times U_2 \times (P_2 \times D + G_2)) \\ & \xrightarrow{\gamma_1 \times \text{id} + \text{id} \times \gamma_2 + \gamma_1 \times \gamma_2} (U_1 \times (\mathbb{D} + 1)) \times U_2 + U_1 \times (U_2 \times (\mathbb{D} + 1)) + (U_1 \times (\mathbb{D} + 1)) \times (U_2 \times (\mathbb{D} + 1)) \\ & \xrightarrow{\simeq} U_1 \times U_2 \times (\mathbb{D} + 1) + U_1 \times U_2 \times (\mathbb{D} + 1) + U_1 \times U_2 \times (\mathbb{D} + 1)^2 \xrightarrow{\nabla + \text{id}} \\ & U_1 \times U_2 \times (\mathbb{D} + 1) + U_1 \times U_2 \times (\mathbb{D} + 1) \times U_2(\mathbb{D} + 1) \xrightarrow{\simeq} U_1 \times U_2 \times ((\mathbb{D} + 1) + (\mathbb{D} + 1))^2 \end{aligned}$$

and

$$\rho_{c_1 \boxtimes c_2} = U_1 \times U_2 \xrightarrow{\rho_1 \times \rho_2} (\mathbb{D} + 1)^{R_1} \times (\mathbb{D} + 1)^{R_1} \xrightarrow{\simeq} (\mathbb{D} + 1)^{R_1 + R_2}$$

3.2 Hook

As emphasized by its name, the *hook* combinator plugs ports with opposite polarity, within an arbitrary connector

$$c = \langle u \in U, \langle \gamma_c, \rho_c \rangle : U \longrightarrow (U \times (\mathbb{D} + 1))^{P \times \mathbb{D} + G} \times (\mathbb{D} + 1)^R \rangle$$

There are two possible plugging situations:

1. Plugging a post port p_i to a read r_j one, resulting in

$$\begin{aligned} \rho_{c \uparrow r_j^{p_i}} &= \langle r_1, \dots, r_{j-1}, r_{j+1}, \dots, r_R \rangle \\ \overline{\gamma_{c \uparrow r_j^{p_i}}} &= U \times ((P-1) \times D + G) \xrightarrow{\theta \times \text{id}} U \times ((P-1) \times D + G) \\ &\xrightarrow{\simeq} \sum_{P-1} U \times D + \sum_G U \xrightarrow{[p_1, \dots, p_{i-1}, p_{i+1}, \dots, p_P] + [g_1, \dots, g_G]} \\ U + U \times (\mathbb{D} + 1) &\xrightarrow{\simeq} U \times 1 + U \times (\mathbb{D} + 1) \\ &\xrightarrow{[\text{id} \times \iota_2, \text{id}]} U \times (\mathbb{D} + 1) \end{aligned}$$

where $\theta : U \rightarrow U$

$$\begin{aligned} \theta &= U \xrightarrow{\Delta} U \times U \xrightarrow{\text{id} \times r_j} U \times \mathbb{D} + 1 \\ &\xrightarrow{\simeq} U \times \mathbb{D} + U \xrightarrow{\overline{p_i} + \text{id}} U + U \xrightarrow{\nabla} U \end{aligned}$$

2. Plugging a post port p_i to a get g_j one, resulting in

$$\begin{aligned} \rho_{c \uparrow g_j^{p_i}} &= \rho_c \\ \overline{\gamma_{c \uparrow g_j^{p_i}}} &= U \times ((P-1) \times D + (G-1)) \xrightarrow{\theta \times \text{id}} \\ &U \times ((P-1) \times D + (G-1)) \\ &\xrightarrow{\simeq} \sum_{P-1} U \times D + \sum_{G-1} U \\ &\xrightarrow{[p_1, \dots, p_{i-1}, p_{i+1}, \dots, p_P] + [g_1, \dots, g_{j-1}, g_{j+1}, \dots, g_G]} \\ U + U \times (\mathbb{D} + 1) &\xrightarrow{\simeq} U \times 1 + U \times (\mathbb{D} + 1) \\ &\xrightarrow{[\text{id} \times \iota_2, \text{id}]} U \times (\mathbb{D} + 1) \end{aligned}$$

where $\theta : U \rightarrow U$

$$\begin{aligned} \theta &= U \xrightarrow{g_j} U \times (\mathbb{D} + 1) \xrightarrow{\simeq} U \times \mathbb{D} + U \\ &\xrightarrow{\overline{p_i} + \text{id}} U + U \xrightarrow{\nabla} U \end{aligned}$$

Note that, according to this definition, if the result of a reaction at a read or get port is of type **1**, which encodes the absence of any data item at the port, the associated post is not activated and, consequently, the interaction does not become effective.

The *hook* combinator can be applied to a whole sequence of pairs of opposite polarity ports, the definitions above extending in a standard way.

The two combinators introduced in this section can be used together to define a form of *sequential composition* in situations where all the **post** ports of the second operand (grouped in *in*) are connected to all the **read** and **get** ports of the first (grouped in *out*). Formally, define by abbreviation

$$c_1 ; c_2 \stackrel{\text{abv}}{=} (c_1 \boxtimes c_2) \uparrow_{out}^{in} \quad (17)$$

4 Examples

This section discusses how some typical software connectors can be defined in the model proposed in this paper.

4.1 Broadcasters and Mergers

Our first example is the *broadcaster*, a connector which replicates in each of its two (output) end-points, any input received in its (unique) entry. There are two variants of this connector, depicted bellow, denoted, respectively, by \blacktriangleleft and \triangleleft . The first one corresponds to a *synchronous* broadcast, in the sense that the two **get** ports are activated simultaneously. The other one is *asynchronous*, which means that it allows for independent activation of any of the **get** ports. The

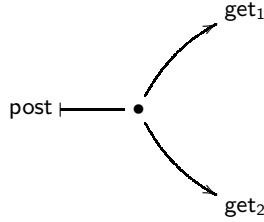


Fig. 1. The *broadcaster* connector.

definition of \triangleleft is rather straightforward as a coalgebra over $U = \mathbb{D} + \mathbf{1}$ and operations

$$\begin{aligned} \overline{\text{post}} &: U \times \mathbb{D} \rightarrow U \\ &= \iota_1 \cdot \pi_2 \\ \text{get}_1 = \text{get}_2 &: U \rightarrow U \times (\mathbb{D} + \mathbf{1}) \\ &= \Delta \end{aligned}$$

where Δ is the *diagonal* function, defined by $\Delta = \langle \text{id}, \text{id} \rangle$. The synchronous case, however, requires the introduction of two boolean flags initialized to $\langle \text{false}, \text{false} \rangle$

to witness the presence of `get` requests at both ports. The idea is that a value is made present at both the `get` ports if it has been previously received, as before, and there exists two reading requests pending. Formally, let $U = (\mathbb{D} + \mathbf{1}) \times (\mathcal{B} \times \mathcal{B})$ and define

$$\begin{aligned} \overline{\text{post}} &: U \times \mathbb{D} \rightarrow U \\ &= \langle \iota_1 \cdot \pi_2, \pi_2 \cdot \pi_1 \rangle \\ \text{get}_1 &: U \rightarrow U \times (\mathbb{D} + 1) \\ &= (=_* \cdot \pi_1 \rightarrow \langle \text{id}, \iota_1 \cdot \pi_1 \rangle, \text{getaux}_1) \end{aligned}$$

where

$$\text{getaux}_1 = (\pi_2 \cdot \pi_2 \rightarrow \langle (\iota_2 \cdot \ast) \times (\underline{\text{false}} \times \underline{\text{false}}), \iota_1 \cdot \pi_1 \rangle, \langle \text{id} \times (\underline{\text{true}} \times \text{id}), \iota_2 \cdot \ast \rangle)$$

The definition of `get2` is similar but for the boolean flags update:

$$\text{getaux}_2 = (\pi_1 \cdot \pi_2 \rightarrow \langle (\iota_2 \cdot \ast) \times (\underline{\text{false}} \times \underline{\text{false}}), \iota_1 \cdot \pi_1 \rangle, \langle \text{id} \times (\text{id} \times \underline{\text{true}}), \iota_2 \cdot \ast \rangle)$$

Dual to the *broadcaster* connector is the *merger* which concentrates messages arriving at any of its two `post` ports. The *merger*, denoted by \triangleright , is similar to

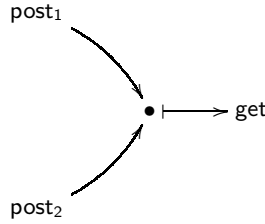


Fig. 2. The *merger* connector.

an asynchronous channel, as given in section 2, with two identical `post` ports. Another variant, denoted by \blacktriangleright , accepts one data item a time, after which disables both `post` ports until `get` is activated. This connector is defined as a coalgebra over $U = \mathbb{D} + \mathbf{1}$ with

$$\begin{aligned} \overline{\text{post}}_1 = \overline{\text{post}}_2 &: U \times \mathbb{D} \rightarrow U \\ &= (=_* \cdot \pi_1 \rightarrow \pi_1, \iota_1 \cdot \pi_2) \\ \text{get} &: U \rightarrow U \times (\mathbb{D} + 1) \\ &= (=_* \rightarrow \langle \text{id}, \iota_2 \cdot \ast \rangle, \langle \iota_2 \cdot \ast, \pi_1 \rangle) \end{aligned}$$

4.2 Synchronization Barrier

In the coordination literature a *synchronization barrier* is a connector used to enforce mutual synchronization between two channels (σ_1 and σ_2 below). It is

achieved by the composition of two synchronous broadcasters with two of their post ports connected by a synchronous drain. As expected, data items read at extremities o_1 and o_2 are read simultaneously. The composition pattern is depicted in figure 3, which corresponds to the following expression:

$$(\leftarrow \boxtimes \leftarrow) ; ((\bullet \xrightarrow{\sigma_1} \bullet) \boxtimes (\bullet \xrightarrow{\nabla} \bullet) \boxtimes (\bullet \xrightarrow{\sigma_2} \bullet)) \quad (18)$$

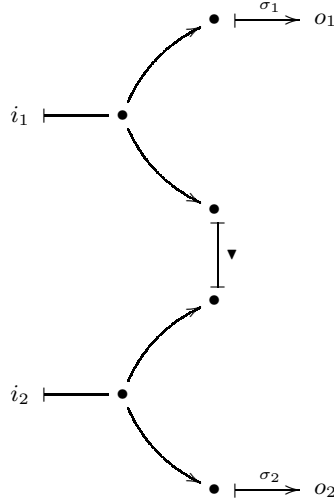


Fig. 3. A *synchronization barrier*.

4.3 The Dining Philosophers

Originally posed and solved by Dijkstra in 1965, the *dinning philosophers* problem provides a good example to experiment an exogenous coordination model of the kind proposed in this paper ¹. In the sequel we discuss two possible solutions to this problem.

A merger-drain solution. One possible solution assumes the existence of five replicas of a component *Phi*(osopher), each one with four *get* ports, two on the lefthand side and another two on the righthand side. The port labeled $left_i$ is activated by Phi_i to place a request for the left fork; port $leftf_i$ on its

¹ The basic version reads as follows. Five philosophers are seated around a table. Each philosopher has a plate of spaghetti and needs two forks to eat it. When a philosopher gets hungry, he tries to acquire his left and right fork, one at a time, in either order. If successful in acquiring two forks, he eats for a while, then puts down the forks and continues to think.

release (and similarly for the ports on the right). Coordination between them is achieved by a software connector **Fork** with four post ports, to be detailed below. The connection between two adjacent philosophers through a **Fork** is depicted below which corresponds to the following expression in the calculus

$$(Phi_i \boxtimes Fork_i \boxtimes Phi_{i+1}) \uparrow_{\text{right}_i \text{ rightf}_i \text{ left}_{i+1} \text{ leftf}_{i+1}}^{rr_i \text{ rf}_i \text{ lr}_i \text{ lf}_i} \quad (19)$$

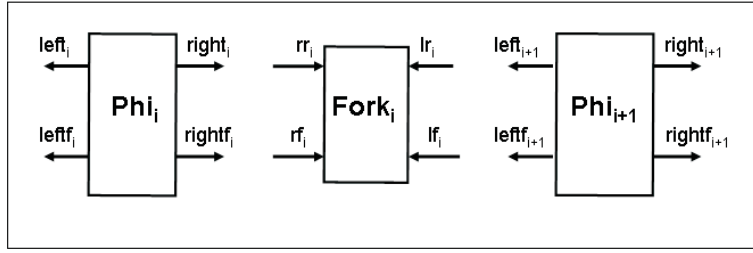


Fig. 4. Dining Philosophers (1).

The synchronization constraints of the problem are dealt by connector **Fork** built from two blocking mergers and a synchronous drain depicted in figure 5 and given by expression

$$(\blacktriangleright \boxplus \blacktriangleright) ; \bullet \xrightarrow{\nabla} \bullet \quad (20)$$

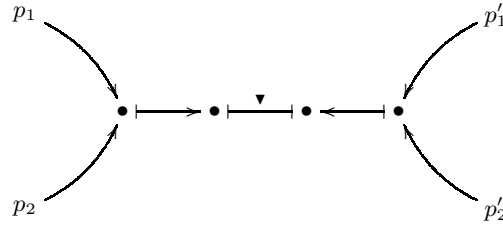


Fig. 5. A *Fork* connector (1).

A token solution. Another solution is based on a specification of **Fork** as an *exchange token* connector. Such a connector is given as a coalgebra over

$U = \{\clubsuit\} + \mathbf{1}$, where \clubsuit is the token representing the (physical) fork. For a philosopher requesting a fork equivaes to an attempt to remove \clubsuit from the *exchange token* connector state space. Dually, a fork is released by returning it to the connector state space. In detail, a fork request at a philosopher port, say *right*, which is a *post* port hooked to (the *get* port) *rr* of the connector is only succesful if the token is available. Otherwise the philosopher must wait until a fork is released. The port specifications for *Fork* are as follows

$$\begin{aligned} \overline{rr} &= \overline{lr} : U \rightarrow U \times (\mathbb{D} + 1) \\ &= (=_{\clubsuit} \rightarrow (\iota_2 \cdot \clubsuit) \times (\iota_1 \cdot \clubsuit), \text{id} \times (\iota_2 \cdot \clubsuit)) \\ \overline{rf} &= \overline{lf} : U \times \mathbb{D} \rightarrow U \\ &= \iota_1 \cdot \clubsuit \end{aligned}$$

Again, the *Fork* connector is used as a mediating agent between any two philosophers as depict in figure 6. The corresponding expression is

$$(Phi_i \boxtimes Fork_i \boxtimes Phi_{i+1}) \begin{matrix} \leftarrow_{rr_i} \text{right}_i \text{ rf}_i \text{ left}_i \text{ lf}_i \\ \leftarrow_{rr_i} \text{rightf}_i \text{ lr}_{i+1} \text{ leftf}_{i+1} \end{matrix} \quad (21)$$

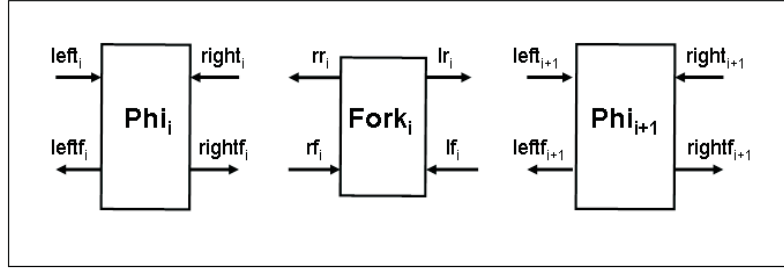


Fig. 6. Dining Philosophers (2).

5 Conclusions and Future Work

This paper discussed the formalization of software connectors, adopting a coordination oriented approach to deal effectively with components' temporal and spatial and support looser levels of inter-component dependency. Two alternative models were presented: relations on time-tagged domains (detailed in [7]) and (polynomial) coalgebras, regarded as relations extended in time, emphasized here. The close relation between the two models is still object of on-going work. In particular, how does such a relation extends when, in the relational model, more

complex notions of time are adopted? Note that, in most cases, the usual set-theoretic universe underlying our coalgebras will not have enough structure to extend such relations over (richer structured) time labels.

Resorting to coalgebras to specify software connectors has the main advantage of being a smooth extension of the previous relational model. Actually, any relation can be seen as a coalgebra over the singleton set, *i.e.*, $U = \mathbf{1}$. Moreover, techniques of coalgebraic analysis, namely *bisimulation*, can be uniformly used to reason about connectors and, in general, architectural design descriptions. In fact, although in this paper, the emphasis was placed on connector modeling and notational expressive power, the model support a basic calculus in which connector equivalence and refinement can be discussed (along the lines of [17]). The model compares quite well to the more classic stream-based approaches (see *e.g.*, [10, 8, 3]), which can be recovered as the *final* interpretation of the coalgebraic specifications proposed here.

A lot of work remains to be done. Our current concerns include, in particular, the full development of a calculus of software connectors emerging from the coalgebraic model and its use in reasoning about the typical *software architectural patterns* [1, 12] and their laws. How easily this work scales up to accommodate *dynamically re-configurable* architectures, as in, *e.g.*, [11] or [26], remains an open challenging question. We are also currently working on the development of an HASKELL based platform for prototyping this model, allowing the user to define and compose, in an interactive way, his/her own software connectors.

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