

# An introduction to Alloy

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# Alloy in a nutshell

- ✦ Declarative modeling language
- ✦ Automated analysis
- ✦ Lightweight formal method

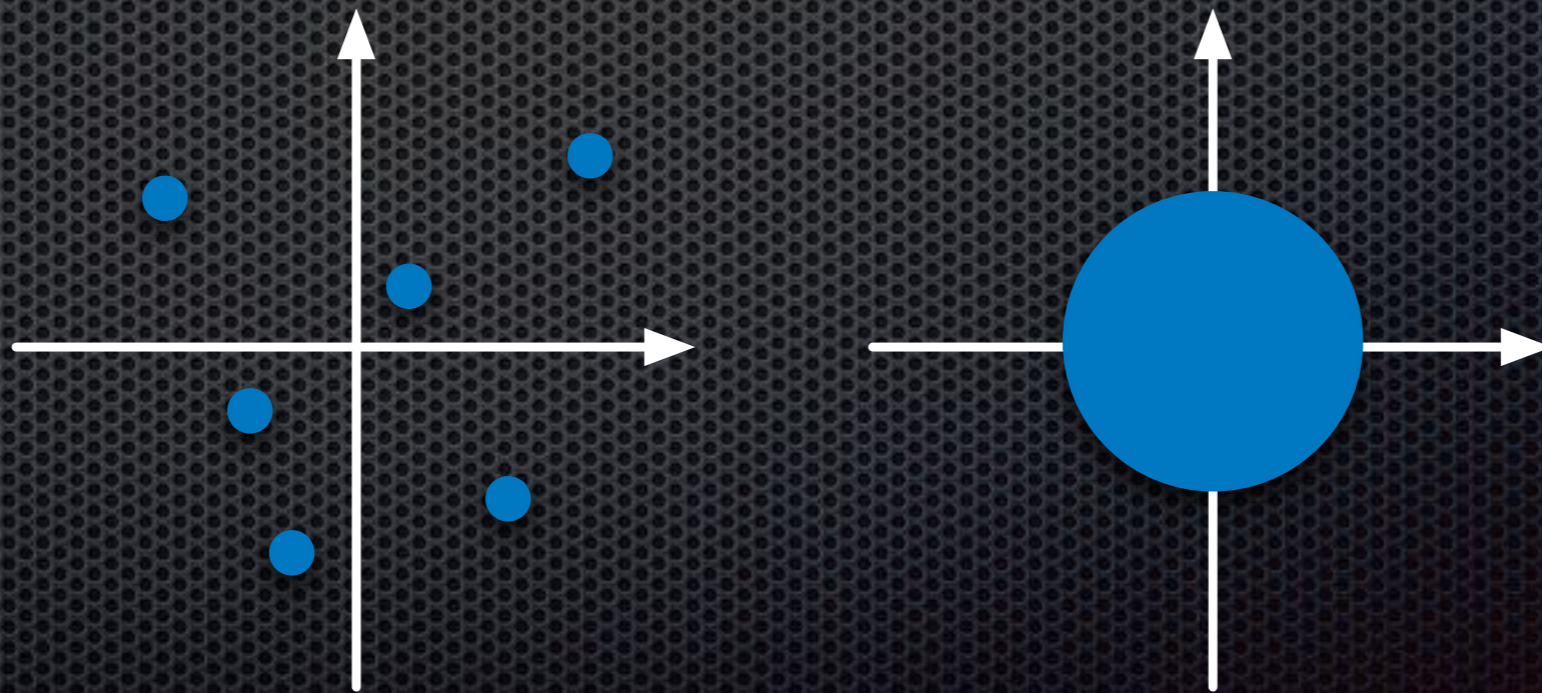
<http://alloy.mit.edu>

# Key ingredients

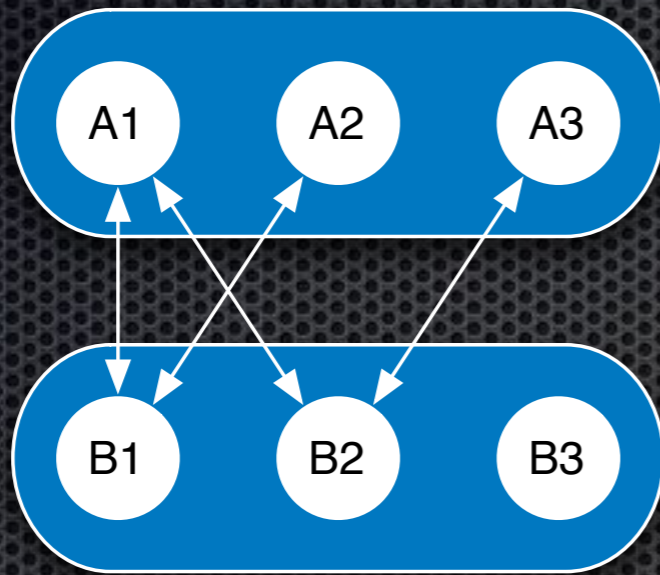
- ✦ Everything is a relation
- ✦ Non-specialized logic
- ✦ Counterexamples within scope
- ✦ Analysis by off-the-shelf SAT solvers

# Small scope hypothesis

- ✦ Most bugs have small counterexamples
- ✦ Instead of building a proof look for a refutation
- ✦ A scope is defined that limits the size of instances



# Relations



A1	B1
A1	B2
A2	B1
A3	B2

$\{(A1, B1), (A1, B2), (A2, B1), (A3, B2)\}$

# Relations

- ✦ Sets are relations of arity 1
- ✦ Scalars are relations with size 1
- ✦ Relations are first order... but we have multirelations

```
File    = {(F1), (F2), (F3)}
Dir     = {(D1), (D2)}
Time   = {(T1), (T2), (T3), (T4)}
root   = {(D1)}
now    = {(T4)}
path   = {(D2)}
parent = {(F1, D1), (D2, D1), (F2, D2)}
log    = {(T1, F1, D1), (T3, D2, D1), (T4, F2, D2)}
```

# The special ones

none	empty set
univ	universal set
iden	identity relation

File = {(F1), (F2), (F3)}

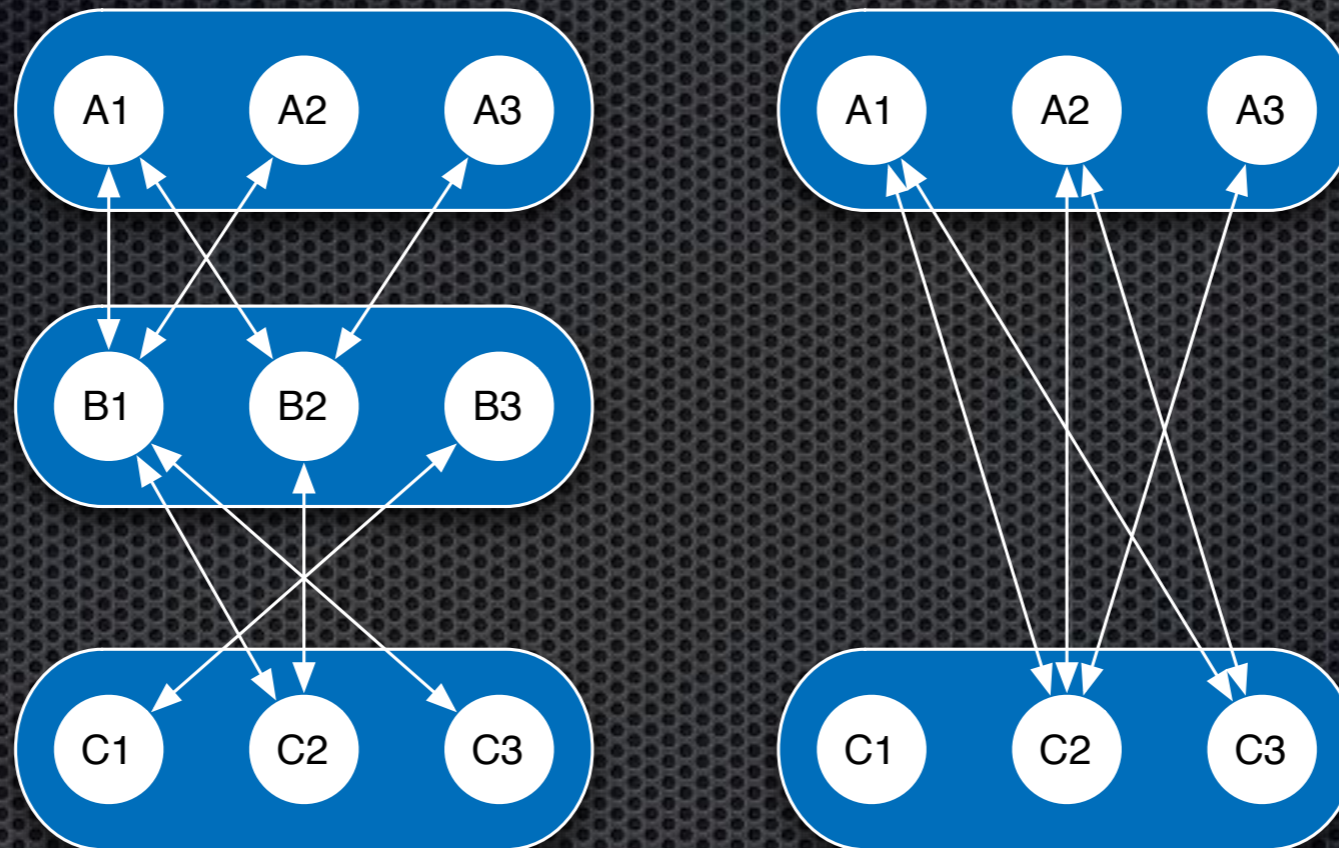
Dir = {(D1), (D2)}

none = {}

univ = {(F1), (F2), (F3), (D1), (D2)}

iden = {(F1, F1), (F2, F2), (F3, F3), (D1, D1), (D2, D2)}

# Composition



$$R = \{(A1, B1), (A1, B2), (A2, B1), (A3, B2)\}$$

$$S = \{(B1, C2), (B1, C3), (B2, C2), (B3, C1)\}$$

$$R.S = \{(A1, C2), (A1, C3), (A2, C2), (A2, C3), (A3, C2)\}$$



# Composition

- ✦ The swiss army knife of Alloy
- ✦ It subsumes function application
- ✦ Encourages a navigational (point-free) style
- ✦  $R.S[x] = x.(R.S)$

```
Person = {(P1), (P2), (P3), (P4)}  
parent = {(P1, P2), (P1, P3), (P2, P4)}  
me = {(P1)}  
me.parent = {(P2), (P3)}  
parent.parent[me] = {(P4)}  
Person.parent = {(P2), (P3), (P4)}
```

# Operators

.	composition
+	union
++	override
&	intersection
-	difference
->	cartesian product
<:	domain restriction
:>	range restriction
~	converse
^	transitive closure
*	transitive-reflexive closure

# Operators

File = {(F1), (F2), (F3)}

Dir = {(D1), (D2)}

root = {(D1)}

new = {(F3, D2), (F1, D1), (F2, D1)}

parent = {(F1, D1), (D2, D1), (F2, D2)}

File + Dir = {(F1), (F2), (F3), (D1), (D2)}

parent + new = {(F1, D1), (D2, D1), (F2, D2), (F3, D2), (F2, D1)}

parent ++ new = {(F1, D1), (D2, D1), (F3, D2), (F2, D1)}

parent - new = {(D2, D1), (F2, D2)}

parent & new = {(F1, D1)}

parent :> root = {(F1, D1), (D2, D1)}

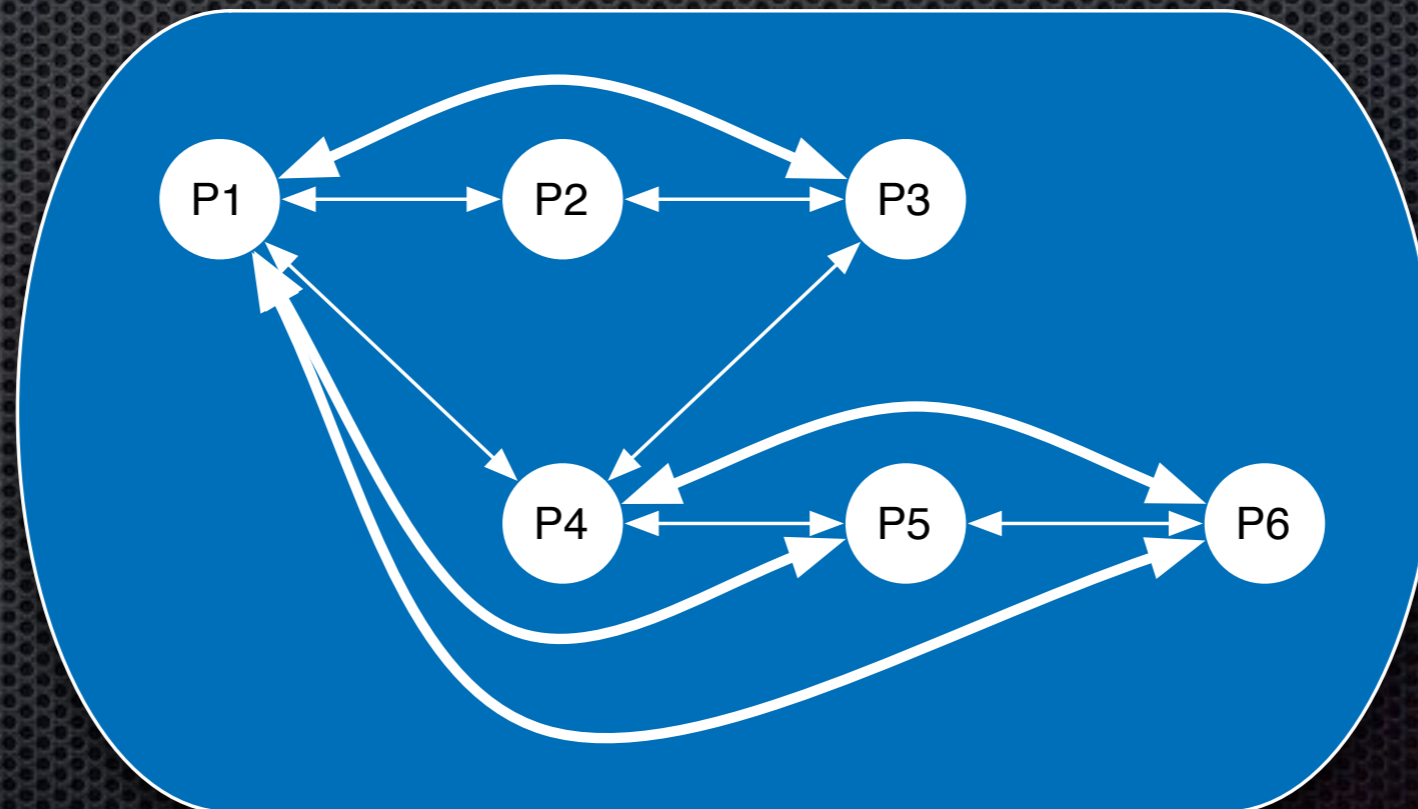
File -> root = {(F1, D1), (F2, D1), (F3, D1)}

new -> Dir = {(F3, D2, D1), (F3, D2, D2), (F1, D1, D1), ...}

~parent = {(D1, F1), (D1, D2), (D2, F2)}

# Closures

- ✦ No recursion... but we have closures
- ✦  $\hat{R} = R + R.R + R.R.R + \dots$
- ✦  $*R = \hat{R} + \text{idem}$



# Multiplicities

$A \ m \rightarrow \ m \ B$	
set	any number
one	exactly one
some	at least one
lone	at most one

# Bestiary

$A \text{ } \lambdaone \rightarrow B$	$A \rightarrow \text{some } B$	$A \rightarrow \lambdaone B$	$A \text{ some } \rightarrow B$
injective	entire	simple	surjective

$A \text{ } \lambdaone \rightarrow \text{some } B$	$A \rightarrow \text{one } B$	$A \text{ some } \rightarrow \lambdaone B$
representation	function	abstraction
$A \text{ } \lambdaone \rightarrow \text{one } B$	$A \text{ some } \rightarrow \text{one } B$	
injection	surjection	
$A \text{ one } \rightarrow \text{one } B$		
bijection		

# Signatures

- ✦ Signatures allow us to introduce sets
- ✦ Top-level signatures are mutually disjoint

```
sig File {}  
sig Dir {}  
sig Name {}
```

# Signatures

- ✦ A signature can extend another signature
- ✦ The extensions are mutually disjoint
- ✦ Signatures can be constrained with a multiplicity

```
sig Object {}  
sig File extends Object {}  
sig Dir extends Object {}  
sig Exe,Txt extends File {}  
one sig Root extends Dir {}
```



# Signatures

- ✦ A signature can be abstract
- ✦ They have no elements outside extensions
- ✦ Arbitrary subset relations can also be declared

```
abstract sig Object {}  
abstract sig File extends Object {}  
sig Dir extends Object {}  
sig Exe, Txt extends File {}  
one sig Root extends Dir {}  
sig Temp in Object {}
```

# Fields

- ✦ Relations can be declared as fields
- ✦ By default binary relations are functions
- ✦ The range can be constrained with a multiplicity

```
abstract sig Object {  
  name: Name,  
  parent: lone Dir  
}  
sig File extends Object {}  
sig Dir extends Object {}  
sig Name {}
```

# Fields

- ✦ Higher arity relations can also be declared as fields
- ✦ Fields can depend on other fields
- ✦ Overloading is allowed for non-overlapping signatures

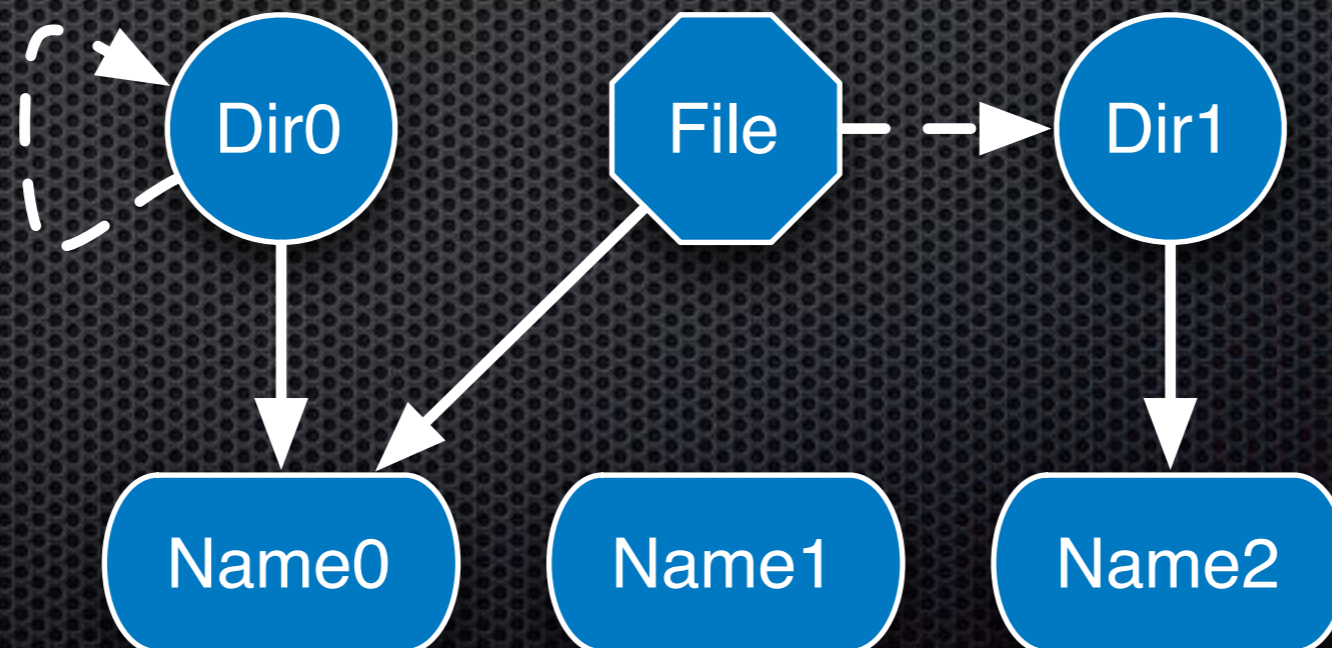
```
abstract sig Object {}  
sig File, Dir extends Object {}  
sig Name {}  
sig FileSystem {  
  objects: set Object,  
  parent: objects -> lone (Dir & objects),  
  name: objects lone -> one Name  
}
```

# Command run

- ✦ Instructs analyzer to search for instances within scope
- ✦ Scope can be fine tuned for each signature
- ✦ The default scope is 3
- ✦ Instances are built by populating sets with atoms up to the given scope
- ✦ Atoms are uninterpreted, indivisible, immutable
- ✦ It returns all (non-symmetric) instances of the model

# Command run

```
abstract sig Object {  
  name: Name,  
  parent: lone Dir  
}  
sig File, Dir extends Object {}  
sig Name {}  
run {} for 3 but 2 Dir, exactly 3 Name
```



# Facts

- ✦ Constraints that are assumed to always hold
- ✦ Be careful what you wish for...
- ✦ First-order logic + relational calculus

```
abstract sig Object {  
  name: Name,  
  parent: lone Dir  
}  
sig File, Dir extends Object {}  
sig Name {}  
fact AllNamesDifferent {}  
fact ParentIsATree {}
```

# Operators

!	not	negation
&&	and	conjunction
	or	disjunction
=>	implies	implication
<=>	iff	equivalence
$A \Rightarrow B \text{ else } C \Leftrightarrow (A \ \&\& \ B) \    \ (!A \ \&\& \ C)$		

# Operators

$=$	equality
$\neq$	inequality
$\text{in}$	is subset
$\text{no}$	is empty
$\text{some}$	is not empty
$\text{one}$	is a singleton
$\text{!one}$	is empty or a singleton



# Quantifiers

$$\Delta x:A \mid P[x]$$

all

P holds for **every** x in A

some

P holds for **at least one** x in A

lone

P holds for **at most one** x in A

one

P holds for **exactly one** x in A

no

P holds for **no** x in A

$$\Delta \text{disj } x,y:A \mid P[x,y] \iff \Delta x,y:A \mid x \neq y \implies P[x,y]$$

# A question of style

- ✦ The classic (point-wise) logic style

```
all disj x,y : Object | name[x] != name[y]
```

- ✦ The navigational style

```
all x : Name | lone name.x
```

- ✦ The multiplicities style

```
name in Object lone -> Name
```

- ✦ The relational (point-free) style

```
name.~name in iden
```

# A static filesystem

```
abstract sig Object {
  name: Name,
  parent: lone Dir
}
sig File, Dir extends Object {}
sig Name {}
fact AllNamesDifferent {
  name in Object lone -> Name // name is injective
}
fact ParentIsATree {
  all f : File | some f.parent // no orphan files
  lone r : Dir | no r.parent // only one root
  no o : Object | o in o.^parent // no cycles
}
```

# Assertions and check

- Assertions are constraints intended to follow from facts of the model
- **check** instructs analyzer to search for counterexamples within scope

```
assert AllDescendFromRoot {  
  lone r : Object | Object in *parent.r  
}
```

```
check AllDescendFromRoot for 6
```

```
check {name in Object lone -> Name <=> name.~name in iden}
```

# Predicates and functions

- ✦ A predicate is a named formula with zero or more declarations for arguments
- ✦ A function also has a declaration for the result

```
fun content [d : Dir] : set Object {  
    parent.d  
}
```

```
pred leaf [o : Object] {  
    o in File || no content[o]  
}
```

# Lets and comprehensions

```
let x = e | P[x]
```

```
{x1 : A1, ..., xn : An | P[x1, ..., xn]}
```

```
fun siblings [o : Object] : set Object {  
  let p = o.parent | parent.p  
}  
check {all o : Object | o in siblings[o]}  
  
fun iden : univ -> univ {  
  {x,y : univ | x = y}  
}
```

# Modules

- ✦ `util/ordering[elem]`
  - ✦ Creates a single linear ordering over atoms in `elem`
  - ✦ Constrains all the permitted atoms to exist
  - ✦ Good for abstracting time, model traces, ...
- ✦ `util/integer`
  - ✦ Collection of utility functions over integers

# Integers

- ✦ Scope for Int defined bitwidth
- ✦ Default semantics is 2's complement arithmetic
- ✦ Be careful with overflows!
- ✦ Forbid overflows semantics also available

```
open util/integer
check {all x,y : Int | pos[y] => gt[add[x,y],x]}
```



# Subtleties of bounded verification

```
sig Set { elems : set Elem }  
sig Elem {}  
  
check {  
  all s0, s1 : Set |  
    some s2 : Set | s2.elems = s0.elems + s1.elems  
}
```

- ✦ Counterexamples are found
- ✦ Set is not “saturated” enough
- ✦ Not all possible sets are forced to exist in an instance

# Subtleties of bounded verification

- ✦ As long as universal quantifiers in runs, or existential quantifiers in checks, are *bounded* there are no problems
- ✦ *Bounded* means that the quantifier scope does not mention names of problematic signatures

```
check {  
  all s0, s1, s2 : Set |  
    s0.elems + s1.elems = s2.elems =>  
      s1.elems + s0.elems = s2.elems  
}
```

# Generator axioms

```
fact SetGenerator {  
  some s : Set | no s.elems  
  all s : Set, e : Elem |  
    some s' : Set | s'.elems = s.elems + e  
}
```

- ✦ A generator axiom could be used to force the existence of all possible sets
- ✦ Unfortunately the scope explodes
- ✦ To verify a model with  $n$  elements  $2^n$  sets are needed
- ✦ Sometimes generator axioms force infinite scopes
- ✦ The risk of inconsistency is very high