

Measuring Inconsistency in Knowledge Bases

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Seminar Presentation

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1 Measuring Inconsistency In Knowledge Bases

- Introduction
- First-Order QC Logic: The Syntax
- First-Order QC Logic: The Semantics
- QC Models
- The Inconsistency Measure
- Extrinsic Inconsistency

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- It is shown that this measure accomplishes also an evaluation of the “intrinsic” inconsistency of a knowledge base;

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- For a formula θ in which $x \in \mathcal{V}$ occurs free, and a constant $d \in D$, define the **substitution** $\theta[x/d]$ **of x by d in θ** as the formula obtained by replacing all occurrences of the free variable x by d ;

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- In the present setting **no rules involving TAUTOLOGIES or CONTRADICTIONS are allowed** in the rewriting process!

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Minimal Model Theorem

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- Recalling the finiteness hypothesis, we define the **measure of inconsistency** for a model M in the context of \mathcal{L} and D (i.e., $\text{Cnfl}(M) \subseteq \text{GrdAt}(\mathcal{L}, D)$) by

$$\text{ModInc}(M, \mathcal{L}, D) := \frac{|\text{Cnfl}(M)|}{|\text{GrdAt}(\mathcal{L}, D)|};$$

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Theorem (Minimal Models for Universal Formulas)

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Uniformity of Inconsistency Measure

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- Thus, even if there exist many different preferred QC models of Δ , all such models have identical inconsistency measures;

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- Thus, for all $M \in \text{PQC}(\mathcal{L}, \Delta_1, D)$, $\text{ModInc}(M, \mathcal{L}, D) = \frac{1}{8}$ and, for all $M \in \text{PQC}(\mathcal{L}, \Delta_2, D)$, $\text{ModInc}(M, \mathcal{L}, D) = \frac{1}{8}$;

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Given \mathcal{L} and Δ , if D_1 and D_2 are two domains of the same size and $M_1 \in \text{PQC}(\mathcal{L}, \Delta, D_1)$, $M_2 \in \text{PQC}(\mathcal{L}, \Delta, D_2)$, then

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- The **extrinsic inconsistency** $\text{ThInc}(\Delta, \mathcal{L})$ of a theory Δ in a language \mathcal{L} is a sequence

$$\langle r_1, r_2, r_3, \dots \rangle,$$

where, for all $n \geq 1$, $r_n = \text{ModInc}(M, \mathcal{L}, D_n)$, where D_n is a domain of size n and $M \in \text{PQC}(\mathcal{L}, \Delta, D_n)$, if such a model exists, and $r_n = *$ (null value), otherwise;

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- The intention is to measure how the inconsistency of Δ in \mathcal{L} evolves as the size of the domain increases;

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Then $\text{ThInc}(\Delta_1, \mathcal{L}) = \langle \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \dots \rangle$ and $\text{ThInc}(\Delta_2, \mathcal{L}) = \langle \frac{1}{2}, \frac{1}{4}, \frac{1}{6}, \dots \rangle$;

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Suppose $\text{ThInc} = \langle x_1, x_2, \dots \rangle$; If $|\mathcal{C}| = k$, $k \geq 1$, then, for all $1 \leq i < k$, $x_i = *$ and, for all $i \geq k$, $x_i \neq *$.

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Suppose $\text{ThInc} = \langle x_1, x_2, \dots \rangle$; If there is an $r_i \in \{r_1, r_2, \dots\}$, such that $r_i = 0$, then $\langle r_1, r_2, \dots \rangle$ is of the form $\langle *, \dots, *, 0, \dots, 0 \rangle$.

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If $\mathcal{L}_1 = \langle \mathcal{C}_1, \mathcal{P}_1 \rangle$ and $\mathcal{L}_2 = \langle \mathcal{C}_2, \mathcal{P}_2 \rangle$, and $\mathcal{L}_1 \subseteq \mathcal{L}_2$ (meaning $\mathcal{C}_1 \subseteq \mathcal{C}_2$ and $\mathcal{P}_1 \subseteq \mathcal{P}_2$), then $\text{ThInc}(\Delta, \mathcal{L}_2) \preceq \text{ThInc}(\Delta, \mathcal{L}_1)$.

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- Then

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 - The theory $\Delta_3 = \{\forall x \exists y (P(x, y) \wedge \neg P(x, y))\}$ has 9 preferred QC models; One is $M_{31} = \{P(a, a), \neg P(a, a), P(b, c), \neg P(b, c), P(c, a), \neg P(c, a)\}$;

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 - The theory $\Delta_3 = \{\forall x \exists y (P(x, y) \wedge \neg P(x, y))\}$ has 9 preferred QC models; One is $M_{31} = \{P(a, a), \neg P(a, a), P(b, c), \neg P(b, c), P(c, a), \neg P(c, a)\}$; So, $\text{ModInc}(M_{31}, \mathcal{L}, D) = \frac{3}{9} = \frac{1}{3}$;

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- Thus $r_n = \text{ModInc}(M, \mathcal{L}, D_n) = \frac{r}{ns}$;

Many Thanks!

MANY THANKS for

- the hospitality
- your attention during the seminar!