

Refinement Algebra for an O-O Language with References

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General context and motivation

Reasoning with pointers and references is difficult

- Aliasing and sharing

New techniques for spatial separation of pointers

- Separation logic, [implicit] dynamic frames, . . .

Few algebraic approaches

- No comprehensive set of algebraic laws for references

General context and motivation

Program semantics

- Operational, denotational, algebraic

The algebraic approach

- Properties as (in)equations (**laws**) relating operators
- No explicit mathematical model
- Modularity and easy mechanisation
- **Soundness and completeness?**

Refinement algebra versus refinement calculus

Calculi by Back, Morgan, Morris, . . .

- Focus on program derivation

Refinement algebra

- Semantic framework
- Applications of program transformation
 - compilation, hw/sw codesign, optimisation, refactorings, patterns, test generation, . . .

Algebra of imperative programming

Language example (cf. Laws of Programming [[Hoare et al/](#)])

<i>Skip</i>	do nothing
abort	unpredictable behaviour
$x, y := e, f$	assignment (possibly multiple)
$c_1; c_2$	sequential composition
$c_1 \sqcap c_2$	nondeterminism
$c_1 \triangleleft b \triangleright c_2$	conditional
$\mu X \bullet c$	recursive program X with body c
X	recursive call
var $v \bullet c$	declaration of v for use in program c

Examples of laws

Law 1 (Sequence associative)

$$(c_1; c_2); c_3 = c_1; (c_2; c_3)$$

Law 2 (Combine assignments)

$$(x := e; x := f) = (x := f[e/x])$$

$f[e/x]$ denotes the substitution of e for x in f

Refinement

- Equality is generally too strong
- Refinement allows more applicable and deterministic implementations

$$(c_1 \sqsubseteq c_2) \hat{=} (c_1 \sqcap c_2 = c_1)$$

- \sqsubseteq is a partial ordering
- Program operators are monotonic wrt \sqsubseteq

A few more laws: recursion

Law 3 (Fixed point) $F(\mu X \bullet F(X)) = \mu X \bullet F(X)$

Law 4 (Least fixed point) $F(Y) \sqsubseteq Y \Rightarrow \mu X \bullet F(X) \sqsubseteq Y$

where F stands for an arbitrary context

Algebra of O-O programming (**copy semantics**)

[Borba, Sampaio]

Law 5 (Move original method to superclass)

```

class B extends A
  ads
  meth m  $\hat{=}$  (sig • b)
  mts
end
class C extends B
  ads'
  meth m  $\hat{=}$  (sig • b')
  mts'
end

```

 $=_{cds,c}$

```

class B extends A
  ads
  meth m  $\hat{=}$  ( sig •
    b  $\triangleleft$  not(self is C)  $\triangleright$  b'
  )
end
class C extends B
  ads'
  mts'
end

```

provided ...

Algebra of imperative programming with references

$cd ::= \mathbf{class} \ A$ class declaration (record)
 $\overline{f : T}$ field declarations
 \mathbf{end}

$c ::= \dots$
 $| \overline{le} := \overline{e}$ multiple assignment
 $| x \leftarrow \mathbf{new} \ A$ new instance

$le ::= x \mid e.f$ variable, field

...

Aliasing

Let x be a variable, d and e expressions and p and q left expressions

$$\mathit{alias}[x, x] \stackrel{\text{def}}{=} \mathbf{true}$$

$$\mathit{alias}[d.f, e.f] \stackrel{\text{def}}{=} d == e$$

$$\mathit{alias}[p, q] \stackrel{\text{def}}{=} \mathbf{false} \quad \text{otherwise}$$

Field Substitution [Morris, Bornat]

Field Substitution

$$e_d^{e1.f} \stackrel{def}{=} e \llbracket [e1.f := d] / f \rrbracket$$

Conditional Field

$$e.[e1.f := d] \stackrel{def}{=} d \triangleleft e == e_1 \triangleright e.f$$

Field Substitution on Left Expressions

$$(e.f)_d^{e1.g} \stackrel{def}{=} (e_d^{e1.g}).f \quad \text{including when } f \equiv g$$

...

Example of field substitution

Effect of $x.f := e$ on $x.f + y.g + z.f$

$$\begin{aligned}
 (x.f + y.g + z.f)_e^{x.f} &= && \text{(substitution def)} \\
 x.[x.f := e] + y.g + z.[x.f := e] &= && \text{(cond field def)} \\
 (e \triangleleft x == x \triangleright x.f) + y.g + (e \triangleleft x == z \triangleright z.f) &= && (x == x \text{ is true}) \\
 e + y.g + (e \triangleleft x == z \triangleright z.f) & & &
 \end{aligned}$$

Assertions

$$[e] \stackrel{def}{=} \mathbf{skip} \triangleleft e \triangleright \perp$$

Assertions are used to record and spread alias information

$$b \triangleleft e \triangleright c = ([e]; b) \triangleleft e \triangleright c$$

$$b \triangleleft e \triangleright c = b \triangleleft e \triangleright ([\mathbf{not} \ e]; c)$$

$$[e]; (b \triangleleft d \triangleright c) = ([e]; b) \triangleleft d \triangleright ([e]; c)$$

...

We use $[\mathcal{D}e]$ to assert the definedness of expression e

Laws of Assignment

$$[\mathit{alias}[p, q_e^{\hat{p}}]]; p := e; q := d = [\mathit{alias}[p, q_e^{\hat{p}}]]; [\mathcal{D}e]; p := d_e^{\hat{p}}$$

Laws of Assignment

$$[\mathit{alias}[p, \hat{q}_e^p]]; p := e; q := d = [\mathit{alias}[p, \hat{q}_e^p]]; [\mathcal{D}e]; p := d_e^p$$

$$\bar{p}, q, q := \bar{e}, d_1, d_2 = \bar{p}, q := \bar{e}, d_1 \sqcap \bar{p}, q := \bar{e}, d_2$$

Laws of Assignment

$$[\mathit{alias}[p, q_e^{\hat{p}}]]; p := e; q := d = [\mathit{alias}[p, q_e^{\hat{p}}]]; [\mathcal{D}e]; p := d_e^p$$

$$\bar{p}, q, q := \bar{e}, d_1, d_2 = \bar{p}, q := \bar{e}, d_1 \sqcap \bar{p}, q := \bar{e}, d_2$$

$$[\mathbf{not\ alias}[p, q]]; p, q := e, q = [\mathcal{D}q \wedge \mathbf{not\ alias}[p, q]]; p := e$$

Laws of Assignment

$$[\mathit{alias}[p, q_e^p]]; p := e; q := d = [\mathit{alias}[p, q_e^p]]; [\mathcal{D}e]; p := d_e^p$$

$$\bar{p}, q, q := \bar{e}, d_1, d_2 = \bar{p}, q := \bar{e}, d_1 \sqcap \bar{p}, q := \bar{e}, d_2$$

$$[\mathbf{not\ alias}[p, q]]; p, q := e, q = [\mathcal{D}q \wedge \mathbf{not\ alias}[p, q]]; p := e$$

$$p := e; (b \triangleleft d \triangleright c) = (p := e; b) \triangleleft d_e^p \triangleright (p := e; c)$$

...

Laws of **new**

$$x \leftarrow \mathbf{new} A = x \leftarrow \mathbf{new} A; \overline{x.f} := \overline{\mathit{default}(T)}$$

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$$x \leftarrow \mathbf{new} A = x \leftarrow \mathbf{new} A; \overline{x.f} := \overline{\mathit{default}(T)}$$

$$x \leftarrow \mathbf{new} A = x \leftarrow \mathbf{new} A; [x \neq \mathbf{null}]$$

...

Relative Completeness

Theorem Let c be a command in which h does not occur free and assume $refs = freeRefs(c)$. We have

$$c = \mathbf{var} \ h : Heap \bullet load(h, refs); S(c, h); store(h)$$

where $S(c, h)$ is the simulation of c using the explicit heap h

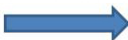
Algebra of O-O programming (**reference semantics**)

```

class A extends B
  priv f:int
  meth m = ( x:T @ c1 )
end
class B extends C
  priv g:D
  meth m = ( x:T @ c2 )
end
...
@ ...; x.m(e); ...

```

Laws of classes
and
O-O commands



```

class A extends B
  pub f:int
end
class B extends C
  pub g:D
end
...
@ ...; ( var x:T @ x:=e; ( μ m @ ... )); ...

```

Laws of commands
with references



```

class A extends B
  pub f:int
end
class B extends C
  pub g:D
end
...
@ var h:Heap @ load(h,...); ...; store(h)

```

Example of derived law

Law 6 (Replace field by temporary)

Consider that the class T declares a field $f : T_f$, then

var $x : T \bullet x \leftarrow \mathbf{new} T; c =$

var $x : T, t : T_f \bullet x \leftarrow \mathbf{new} T; t := x.f; c[t/x.f]; x.f := t$

provided

- (1) t is a fresh variable in c ;
- (2) x is read only, not used as argument nor assigned to variables or fields in c
- (3) if $e.f$ occurs in c then $e \equiv x$.

Rule: Replace Method with Method Object

```

class A extends C
  ads
  meth m  $\hat{=}$  ( $\overline{x:T} \bullet$ 
    var  $\overline{t:R} \bullet$ 
      c[self,  $\overline{x}$ ,  $\overline{t}$ ] )
  mts
end

```

 $=_{cds,b}$

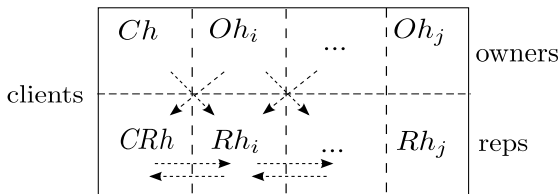
```

class A extends C
  ads
  meth m  $\hat{=}$  ( $\overline{x:T} \bullet$ 
    var s:M
      s  $\leftarrow$  new M(self,  $\overline{x}$ );
      s.m() )
  mts
end
class M extends Object
  pri a:A
  pri  $\overline{x:T}$ 
  pri  $\overline{t:R}$ 
  meth ctr  $\hat{=}$  ( $a:A, \overline{x:T} \bullet$ 
    self.a, self. $\overline{x}$  := a,  $\overline{x}$  )
  meth m  $\hat{=}$  ( $\bullet$ 
    c[self.a, self. $\overline{x}$ , self. $\overline{t}$ ])
end

```


Ownership and Confinement

Data refinement based on confinement notions



Definition. A *local coupling* is a relation between two different representations of Own (one using Rep and other using Rep')

Definition. A *simulation* is a local coupling that is preserved at the creation of Own instances and also at the end of every method call to Own instances.

Change of data Representation

Based on a notion of ownership confinement

Law 7 (Data Refinement of class hierarchies)

$$CS =_{c ds, c} CS'$$

provided

- *cs and cs' are hierarchies with root Own, and cds has no subclasses of Own;*
- *cds, cs is confined for Own, Rep;*
- *cds, cs' is confined for Own, Rep' ;*
- ...
- *There exists a simulation R.*

Rule 1 (Pull up field)

```

class M extends N
  adsm
  mtsm
end
class L extends M
  prot x : T; adsl
  mtsl
end
class K extends M
  prot y : T; adsk
  mtsk
end
cds1

```

 $=_{cds,c}$

```

class M extends N
  prot z : T; adsm
  mtsm
end
class L extends M
  adsl
  mts'l
end
class K extends M
  adsk
  mts'k
end
cds'1

```

where $mts'_l = mts_l[z/x]$, $mts'_k = mts_k[z/y]$
 similar for $cds'_1 \dots$

Some proof steps

- (1) Apply law to move attributes x and y to class M
- (2) Apply data refinement law with $M = Own$, no *Reps* and local coupling:

$$type(\mathbf{self}) = type(\mathbf{self}')$$

$$\wedge (\mathbf{self} \text{ is } L \Rightarrow \mathbf{self}'.z = \mathbf{self}.x)$$

$$\wedge (\mathbf{self} \text{ is } K \Rightarrow \mathbf{self}'.z = \mathbf{self}.y)$$

$$\wedge \forall f \in fields(type(\mathbf{self}))$$

$$f \neq x \wedge f \neq y \Rightarrow \mathbf{self}'.f = \mathbf{self}.f$$

- (3) Prove that this is a simulation

Summary: overall reasoning framework

Patterns		
Refactoring rules		
Command laws	Class laws	Data refinement
Semantics		

Ongoing and future work

- Permissions for framing
 - [implicit] dynamic frames, separation logic
- Ownership + data refinement as in Morgan's calculus
- Proofs of the laws on a relational model
 - Extension of that for Laws of Programming
- More refactorings and design patterns
 - Observer, Flyweight, creational patterns, ...
- Other applications: compiler optimisations
- Mechanisation
 - A major challenge is dealing with refactoring provisos

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More on the semantics of **new**

$$[y == \mathbf{alloc}]; x \leftarrow \mathbf{new} A = \\ [y == \mathbf{alloc}]; x \leftarrow \mathbf{new} A; [x \notin y \wedge \mathbf{alloc} == y \cup \{x\}]$$

More on the semantics of **new**

$$[y == \mathbf{alloc}]; x \leftarrow \mathbf{new} A = \\ [y == \mathbf{alloc}]; x \leftarrow \mathbf{new} A; [x \notin y \wedge \mathbf{alloc} == y \cup \{x\}]$$

As a consequence:

$$x \leftarrow \mathbf{new} A; x \leftarrow \mathbf{new} A \neq x \leftarrow \mathbf{new} A$$

Algebra of concurrent programming

CSP, occam, . . . and respective laws

Some applications:

- Hardware compilers [He *et al*] [Perna *et al*]
- Hardware/software codesign [Silva, Sampaio] [He *et al*]
 $S \sqsubseteq (c_1 \parallel c_2 \parallel \dots \parallel c_n) \sqsubseteq SW \parallel HW_1 \parallel \dots \parallel HW_k$
- Test case generation using CSP and FDR [Nogueira, Sampaio]
 - **assert** $model \sqsubseteq model_{marks}$
 - Industrial partners: Motorola and Embraer